Digital to Analog and Back

- Analog: encoding information using voltage
 - Many sensors use voltage as an output
 - Motors torque is determined by current passing through the motor
- Digital: encoding information with bits

How to move between these?

Analog to Digital Conversion

For a given voltage, what is the digital representation of the voltage?

• How would we implement this?

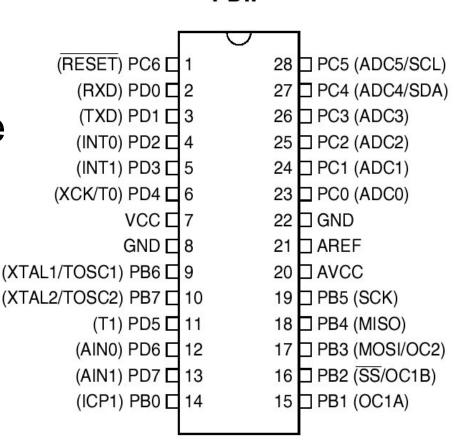
Analog to Digital Conversion

- For a given voltage, what is the digital representation of the voltage?
- Common approach: successive approximation
 - Use a D2A converter to produce a voltage V
 - Compare this with the input voltage Vi
 - If different, then increase/decrease V

- Repeat (stopping when V is close to Vi)

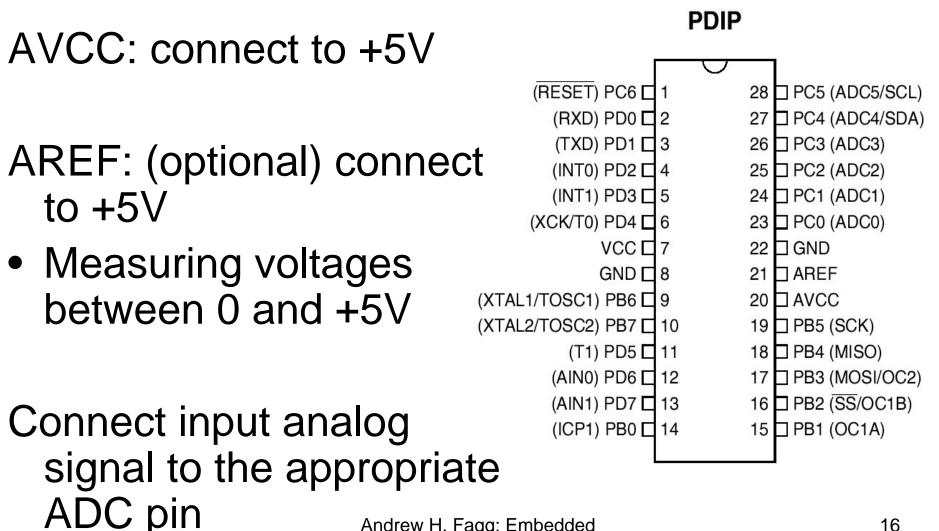
A2D in the Mega8

- The mega8 contains hardware that implements successive approximation
- 6 mega8 pins can be configured as analog input pins



PDIP

A2D in the Mega8



A Code Example

```
// Initialize adc
adc set reference(ADC REF AREF); // Use the AREF reference pin
adc set adlar(0);
adc_set_prescalar(ADC_PRESCALAR_128);
// Turn on ADC Converter
adc_set_enable(ADC_ENABLE);
        :
        :
```

```
long val;
```

// Can do the following an arbitrary number of times

```
adc_set_channel(ADC_CHANNEL_0);
                              // ADC0
// Actually start a conversion
adc_start_conversion();
```

<Could go off and do something else for a while>

val = adc_read(); // Read AndrewsHLoGaggaEmbedded Systems: Analog/Digital

- // For our purposes, always use 0
- // Necessary with 16MHz clock
- // and 10 bit resolution

- All functions are provided in oulib
- See OUlib documentation for the definition of constants
- Can get to the example code from the Atmel HowTo www.cs.ou.edu/~fagg/classes/general/atmel

• Setting the maximum voltage:

adc_set_reference(ADC_REF_AREF); // Use the AREF reference pin

Can also used a fixed voltage (+2.56V):

adc_set_reference(ADC_REF_2p56V);

Determining how fast the conversion requires:

- Conversion requires:
 128 * 15 / 16000000 seconds
 - Can convert faster, but may not get the full 10bit resolution

• Reading out the value:

val = adc_read(); // Read the analog value

- Blocks until conversion is complete
- Will return a value between 0 and 0x3FF (1023)

Other Devices

- External devices are available that will perform D2A and A2D
- Often interface to the microprocessor via I²C or SPI
 - (these are high-speed serial protocols)
- Many options
 - Resolution
 - Conversion speed
 - Number of channels